



TRANSIENT MODELING USING MEAN VALUE ENGINE CYLINDER

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Overview

- **Introduction to Mean Value Modeling**
- **Theory of Mean Value Modeling**
- **Recommended Methodology**
- **Comparisons with Detailed Engine Models**

Intro to Mean Value Models



- **Simplified engine cylinder: maps define air flow and distribution of fuel energy**
 - No combustion or breathing process modeled
 - Faster computations than ‘EngCylinder’
 - Multiple cylinders combined into 1 mean value cylinder
- **Modified Flow system**
 - Parts combined into larger volumes
 - Further improves simulation time
 - Essentially “filling-emptying” models
- **Useful when computation speed and “bulk flow” are important**
 - Engine control system design
 - Transient vehicle simulations

Mean Value Cylinder: Theory



- ‘EngCylMeanV’ defined by three maps
- **Volumetric Efficiency**
 - Air mass flow rate imposed at inlet and outlet of cylinder
- **Indicated Efficiency**
 - Percent of total fuel energy converted into work
- **Exhaust Energy Fraction**
 - Percent of total fuel energy converted into exhaust energy
 - All remaining fuel energy assumed lost to heat transfer
- **Maps can be traditional or use Neural Network & controls**



Recommended Methodology

- **Select Independent Variables**
 - Engineer must know important variables that affect engine and will be studied (RPM, load, manifold conditions, valve timing, etc.)
- **Prepare model to run Sweeps**
 - Remove TC, if applicable
 - Make independent variables parameters
- **Run Sweeps**
 - use DOE Setup
 - Distributed processing
- **Create Neural Networks and Maps**
 - New Neural Network training tool in GT-SUITE
- **Build Model**

Neural Networks & Mean Value Cylinder



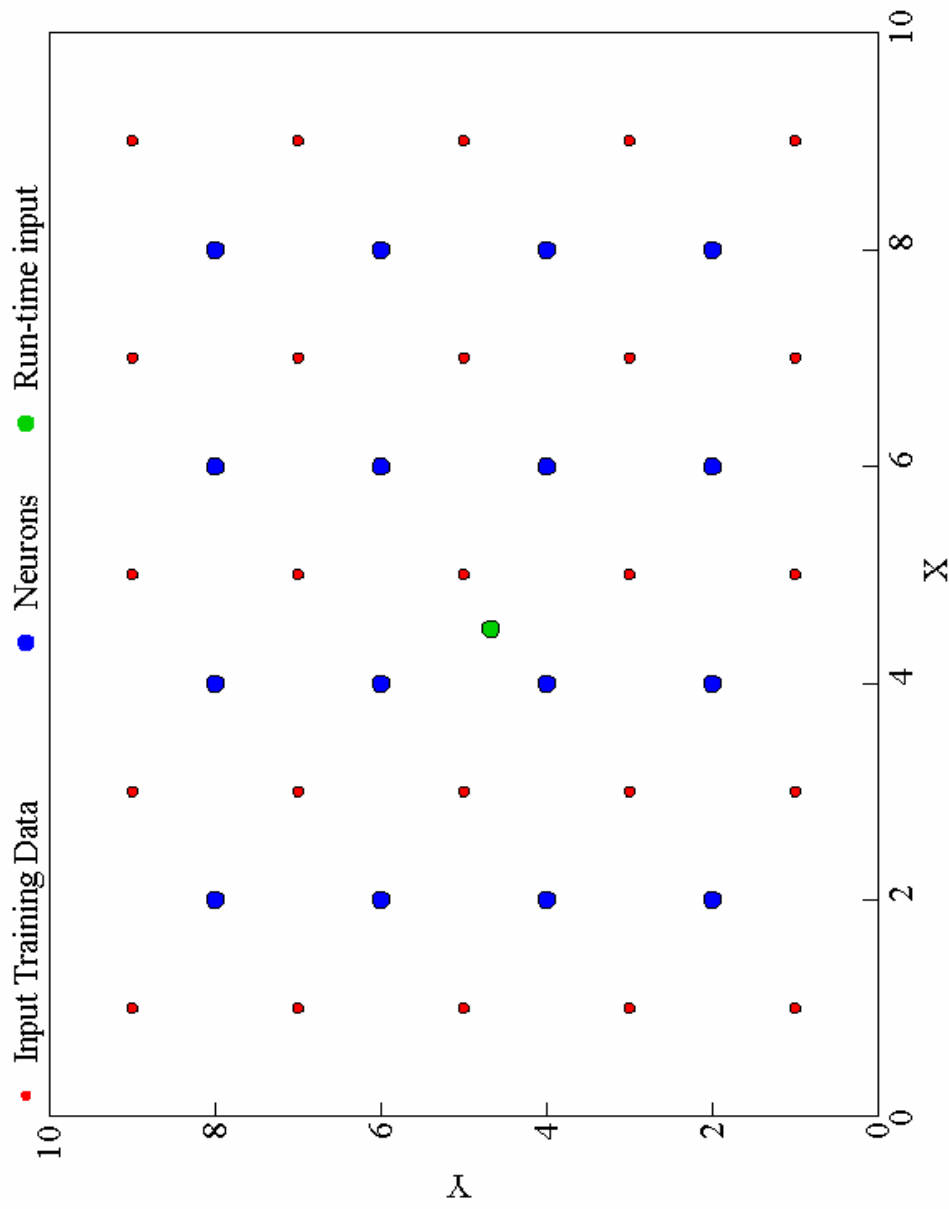
- Lookup tables are OK if variable is function of 1 or 2 RLT variables
- Defining more complex relationships requires the use of controls (dependence on 3 or more variables)
- Mean Value Cylinder require more than 2 inputs
- Neural Networks can be trained to control the mean value cylinder with complex dependencies
 - Faster than simple lookups, typically
 - Can fit data better than linear interpolation
 - Can interpolate 3 or more input values better than lookups



Neural Network

- “Black box”
- “Neurons” work in parallel
- “Taught” to produce output with inputs
- Best fit – not exact
- Neurons placed in domain of input data
- Each neuron assigned math operations
- Output from all neurons is combined to form output

Simple 2-input example





Comparison with Detailed Models

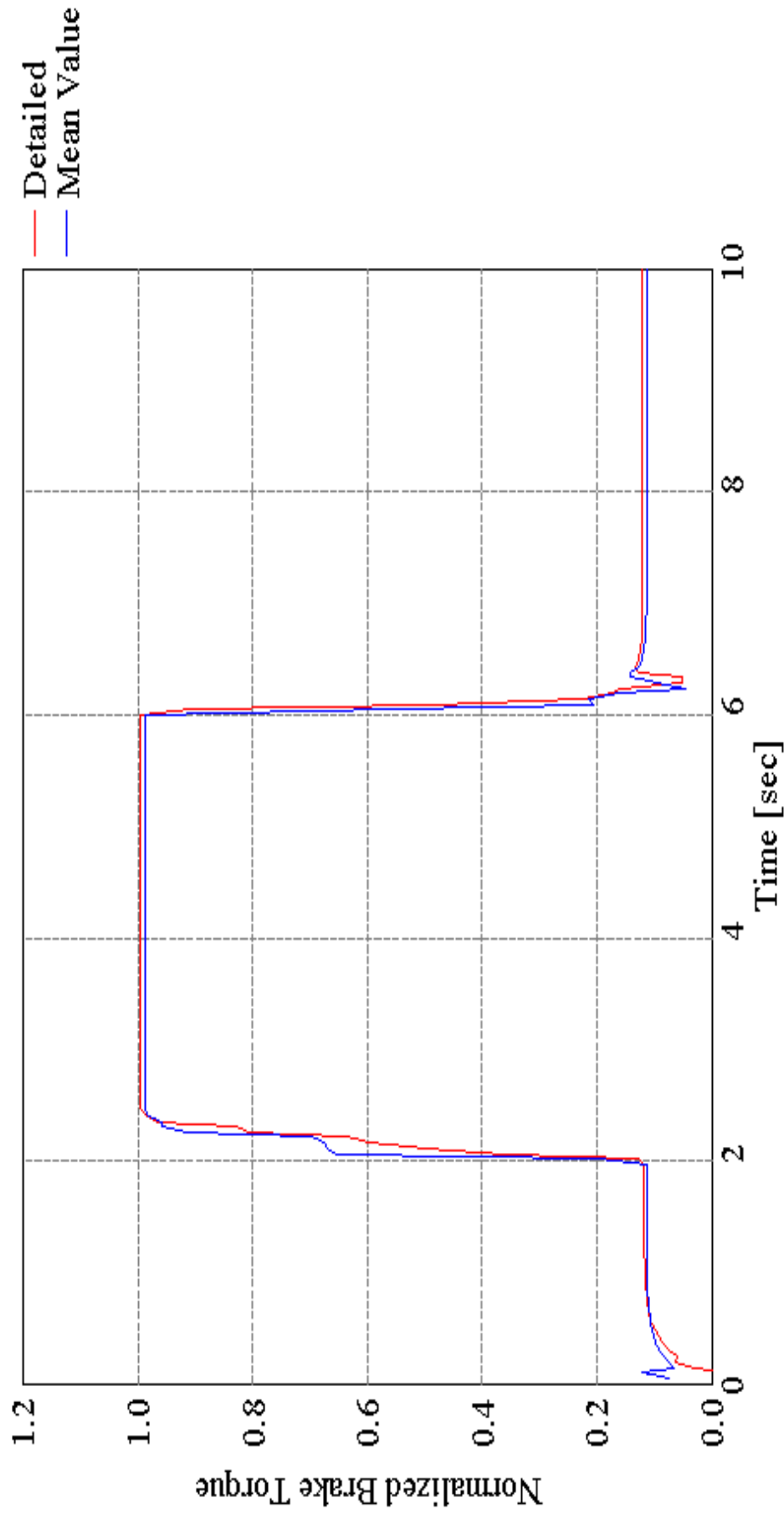
- Naturally aspirated, 6-cylinder, SI engine
 - VVT
 - Wide open throttle test
 - Constant speed throttle test
 - Model provided courtesy of Volvo Cars
- Turbocharged, 4-cylinder, 2.0L, DI engine
 - Steady State comparison
 - Transient comparison
 - Coupled engine-vehicle comparison
 - Made from example ‘injmap’



Naturally Aspirated, SI-Engine

- Wide open throttle test

2500 RPM Step Test - Ambient Temperature = 15C

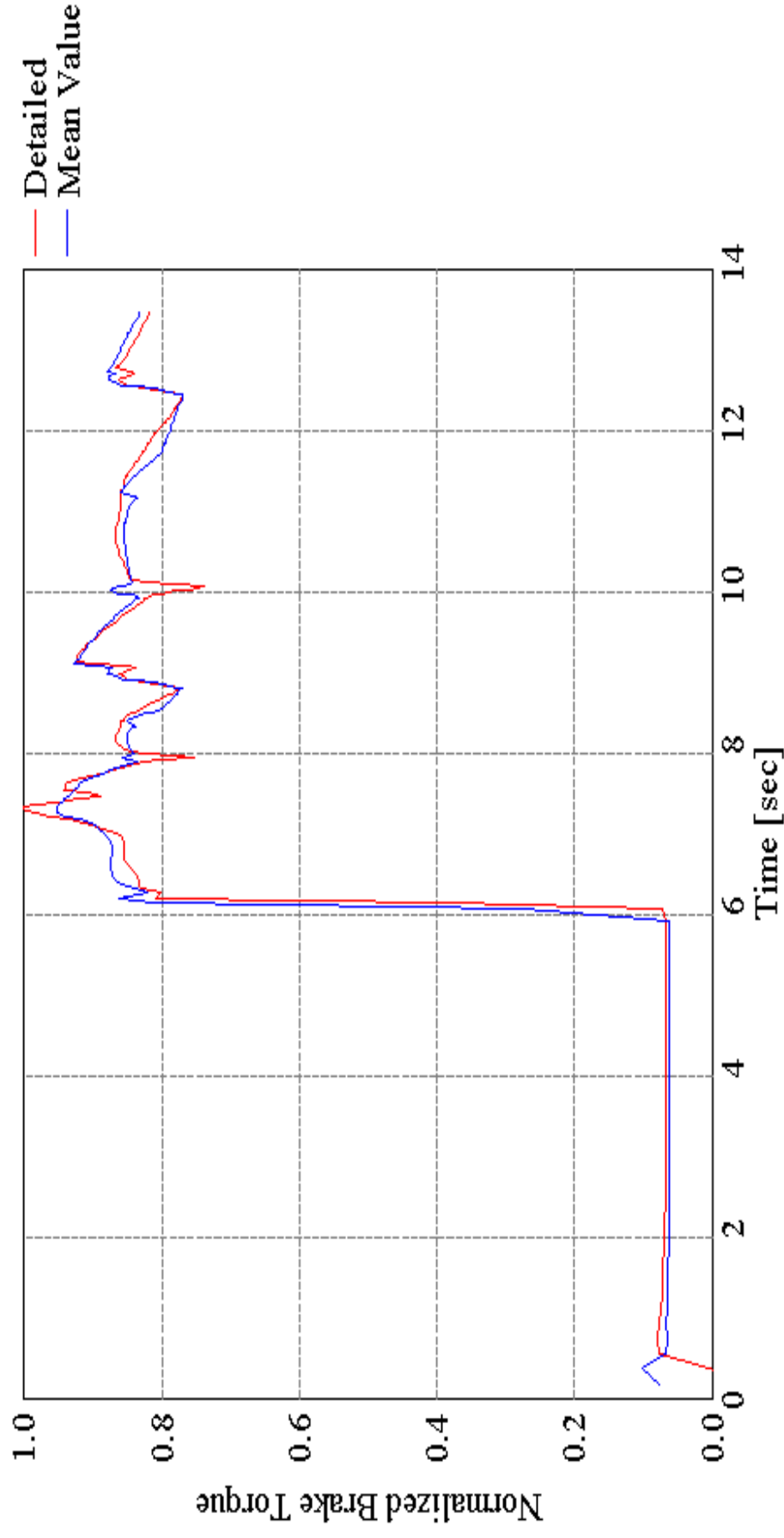




Naturally Aspirated, SI-Engine

- Constant Speed Throttle Step Test

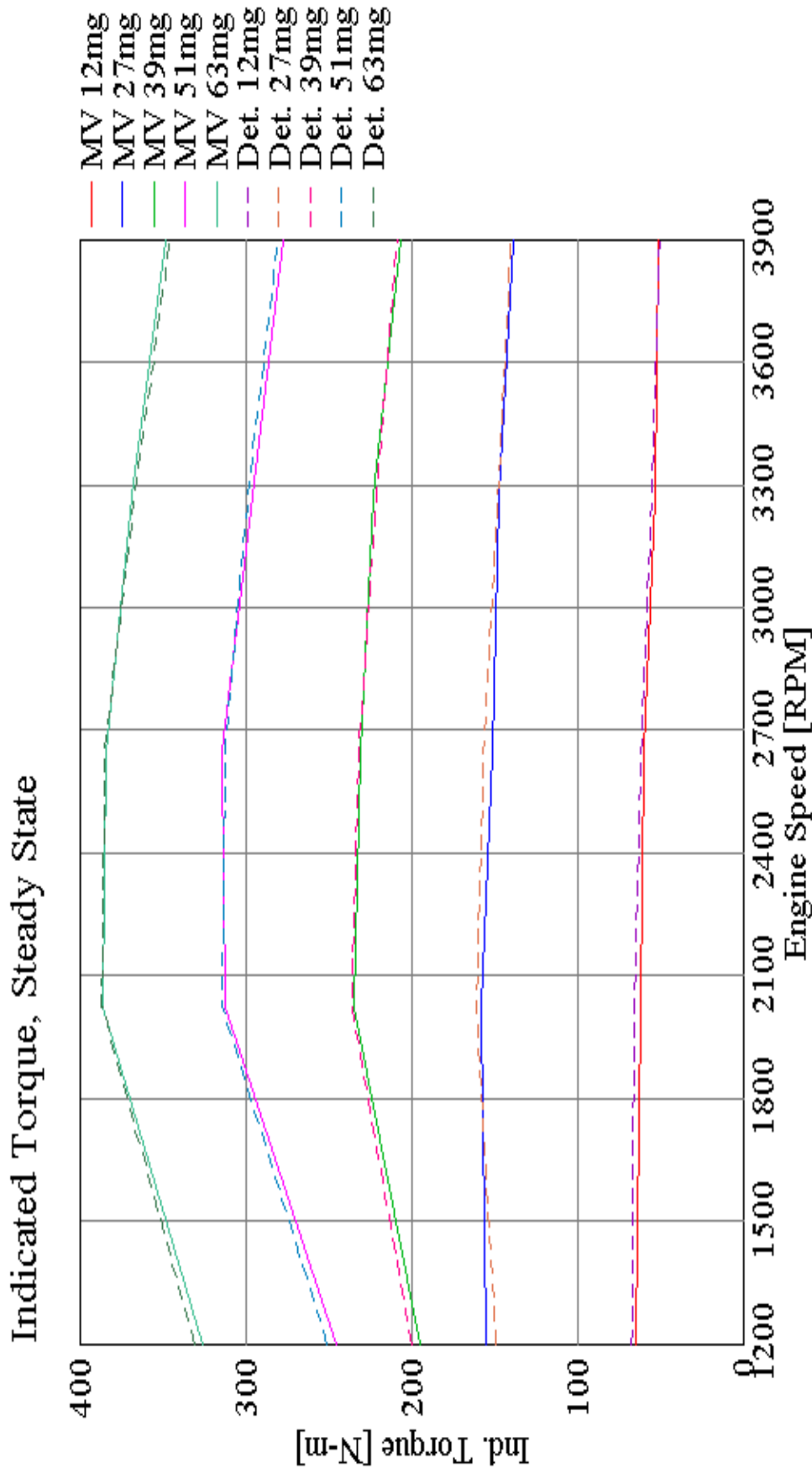
WOT Brake Torque - Ambient Temperature = 15C





Turbocharged, DI Engine

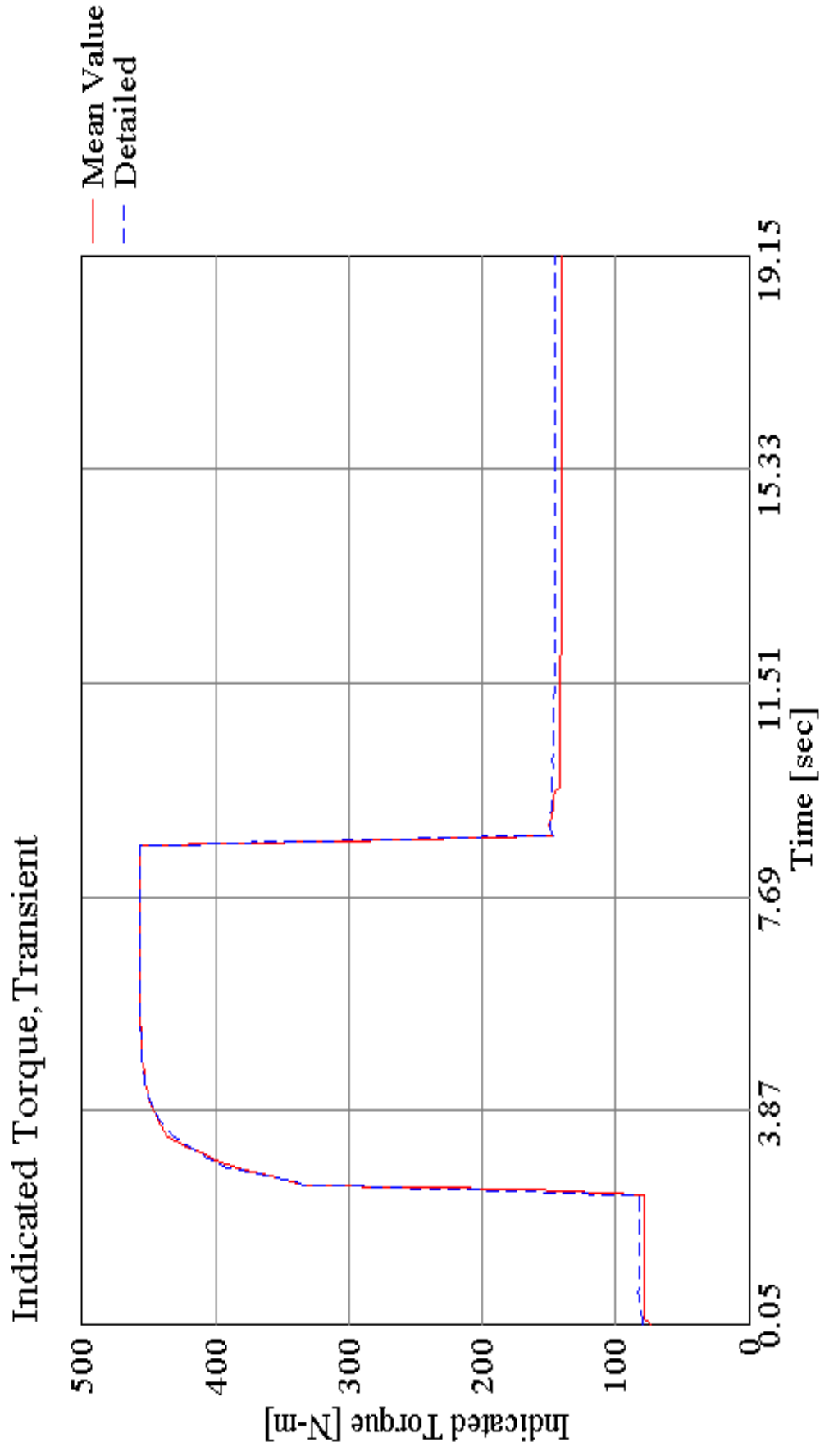
- Indicated torque at steady state for different loads





Turbocharged, DI Engine

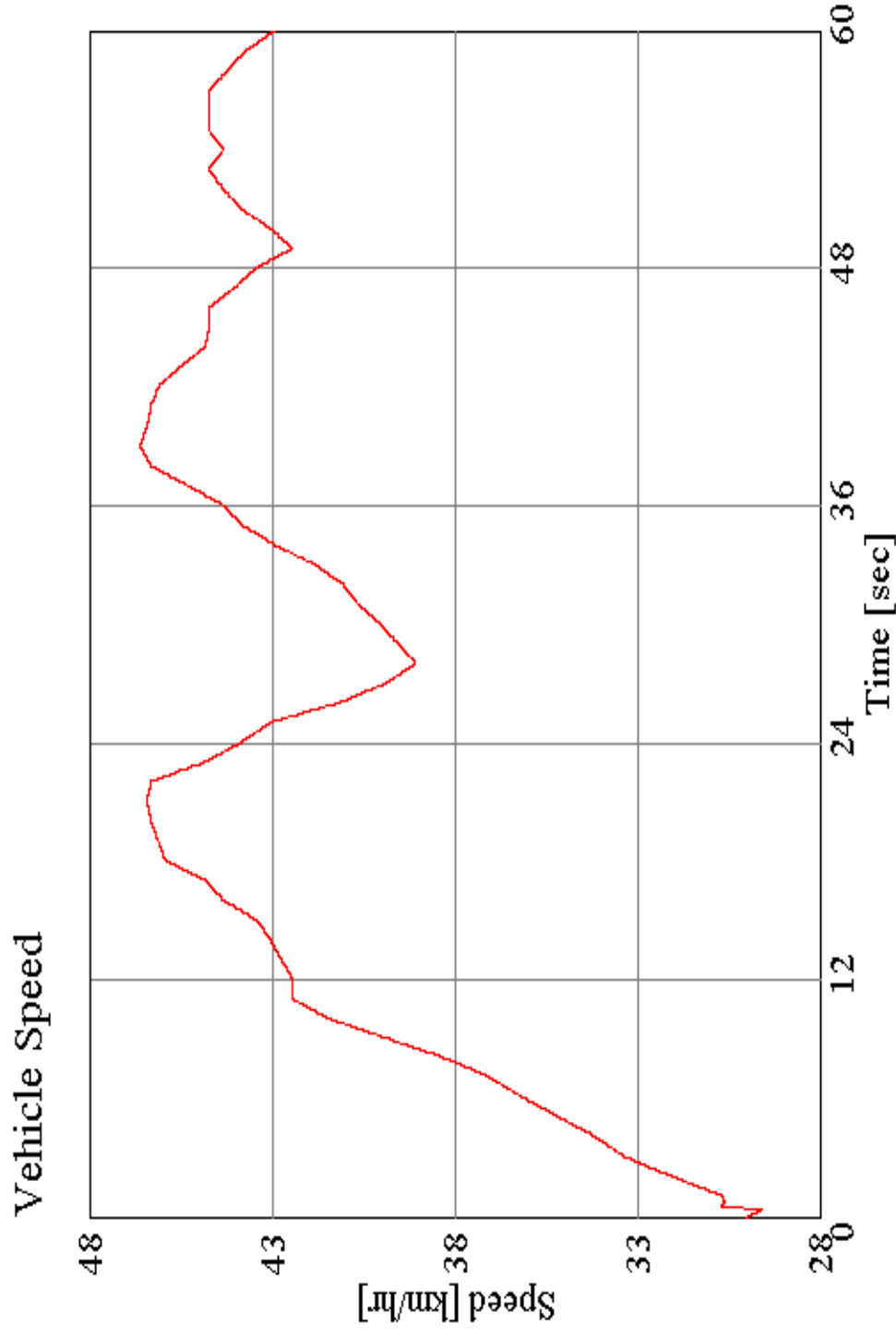
- Comparison of indicated torque during a transient



Turbocharged, DI Engine



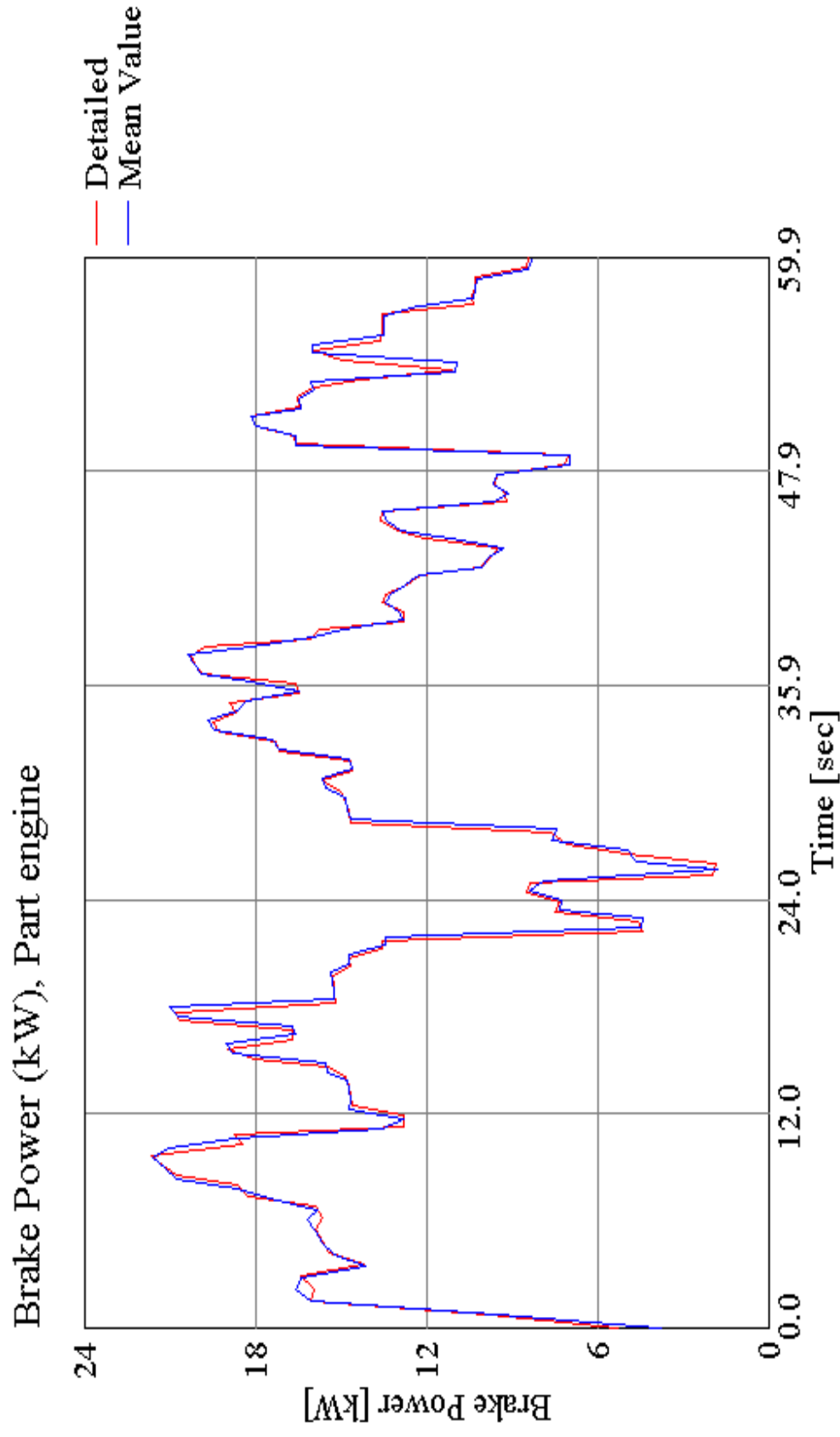
- Virtual Vehicle Simulation – Imposed Vehicle Speed



Turbocharged, DI Engine



- Predicted Brake Power





Turbocharged, DI Engine

- Comparison of Predicted BSFC

BSFC - Brake Specific Fuel Consumption, Part engine

